# Competitive Strategies for Online Clique Clustering

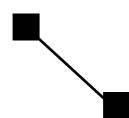
Christoph Dürr

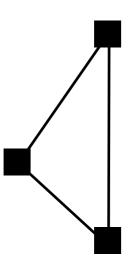
Joint work with
Marek Chrobak
Aleksander Fabijan
Bengt J. Nilsson

Vertices arrive one by one, revealing edges to existing vertices.

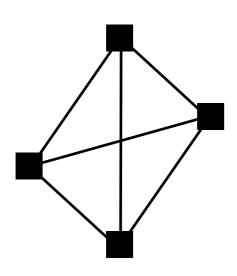
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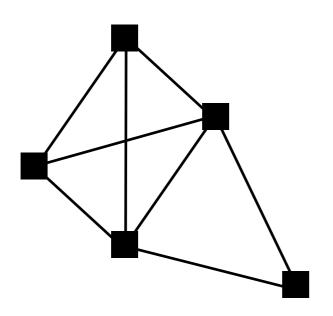




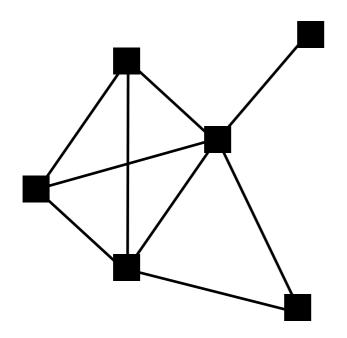
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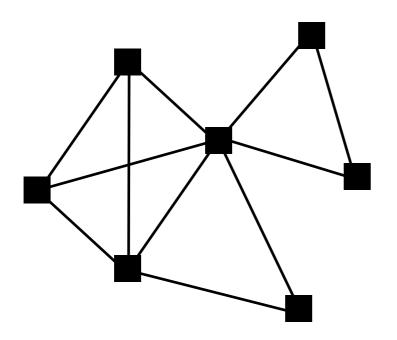
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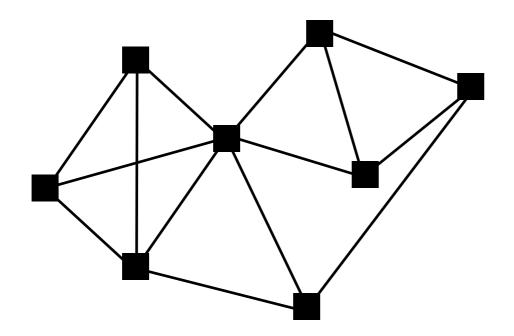
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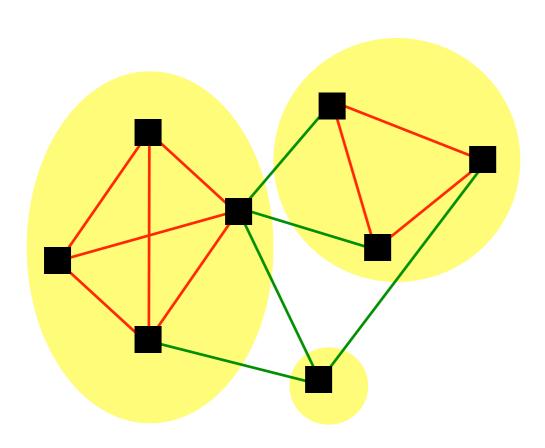


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### Partition a graph into cliques



contribution of a clique of size k is  $\binom{k}{2}$ 

#### Decide:

maintain partition into cliques by merging.
Splitting not allowed.

#### **Objective values:**

#### **MaxCC**

maximize number of edges inside the cliques

#### **MinCC**

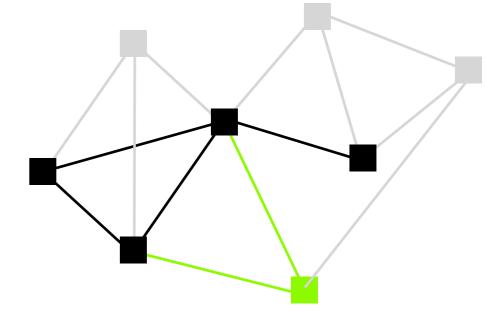
minimize number of edges between the cliques

Motivation: DNA clone classification, gene expression profiling

Offline problem: not approximable within a factor of  $n^{1-o(\epsilon)}$  under some complexity hypothesis

#### Online model

- vertices arrive one by one, revealing adjacent edges
- strategy is allowed to merge cliques,
   but can never split them again



competitive ratio: between obj. value of algorithms solution over optimal obj.
 value for current graph.

competitive ratio	LB	LB for doubling technique	UB
MaxCC	6	10.927	22.641
MinCC	n-2		n-2

• There was a first paper by Fabijan, Nilsson, Persson, CIAC 2013

#### MaxCC

### Online strategy model

- Our strategy needs an oracle that tells him the optimal clustering for some subgraph
- In that sense it is not really an online algorithm serving requests in polynomial time, but rather a "strategy"
- Hence it is ok, for the problem to have constant competitive ratio, even though the
  offline problem cannot be approximated in polynomial time within a constant ratio

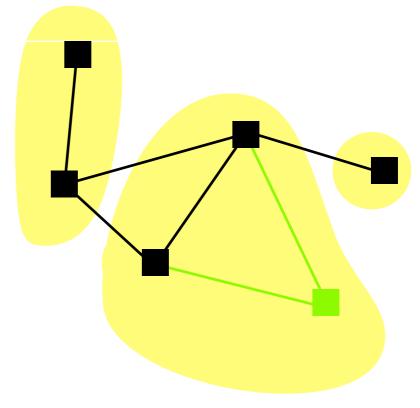


### Our strategy OCC

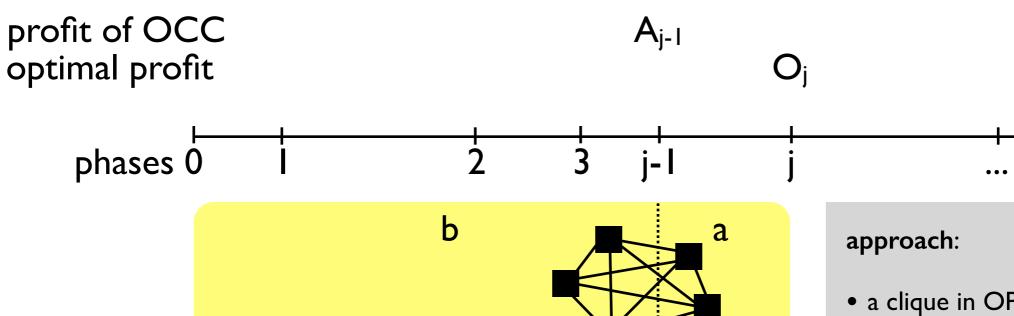
- Parameter γ>1
- stages, starting with j=0
- at each new vertex :
  - place it in a singleton clique
  - if singletons can form a clique partition with profit  $\geq \gamma^{j}$ , then merge according to this partition and move to stage j+1

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#### Upper bound on ratio of OCC



• .. is bounded by a geometric sequence

$$A_j \ge \gamma^0 + \gamma^1 + ... + \gamma^j \ge (\gamma^{j+1} - 1)/(\gamma - 1)$$

• ...

- a clique in OPT is of type

   (a,b), if it has a vertices
   released in phase j and b from previous phases.
- k<sub>ab</sub> := number of cliques in OPT of this type.
- Use these numbers to bound  $A_{j-1}$ , and  $O_j$

• we obtain a rough bound assymptotic ratio  $\leq (3+\sqrt{13})(5+\sqrt{13})^2/(12(\sqrt{13}-1)) \approx 15.645$  for

$$\gamma = (3 + \sqrt{13})/2 \approx 3.303$$

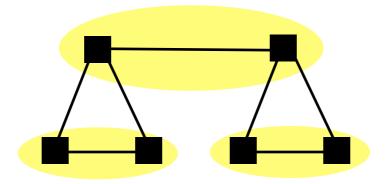
#### The hard life of an online strategy

- Usual Game: adversary release some vertex, strategy makes possibly some clustering, adversary releases ... (and so on, say forever)
- If strategy wants to reach competitive ratio R, he can postpone all merging until

value of current solution \*R < optimal solution for current graph



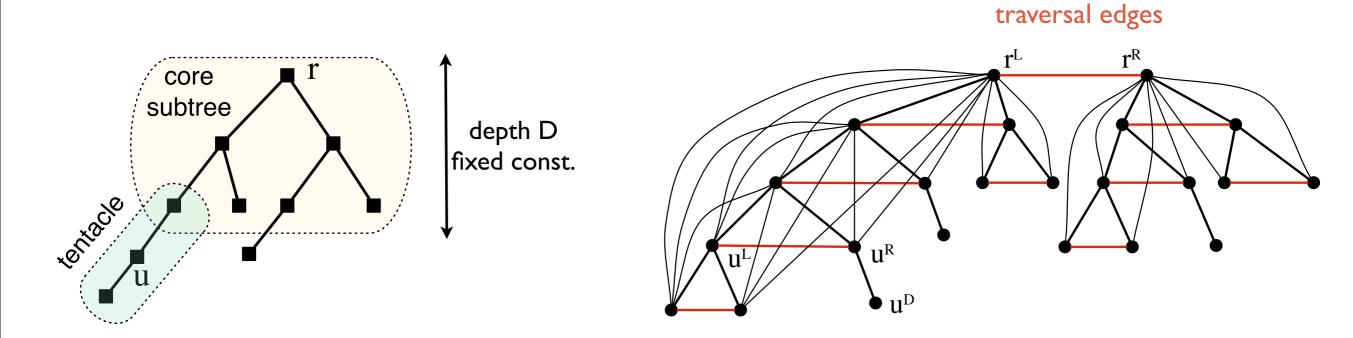
Strategy needs to take the first edge, otherwise ratio is 1/0



But if endpoint is part of a clique, algo. can obtain only part of that clique.
 Ratio is already 6/3, let's improve it ...

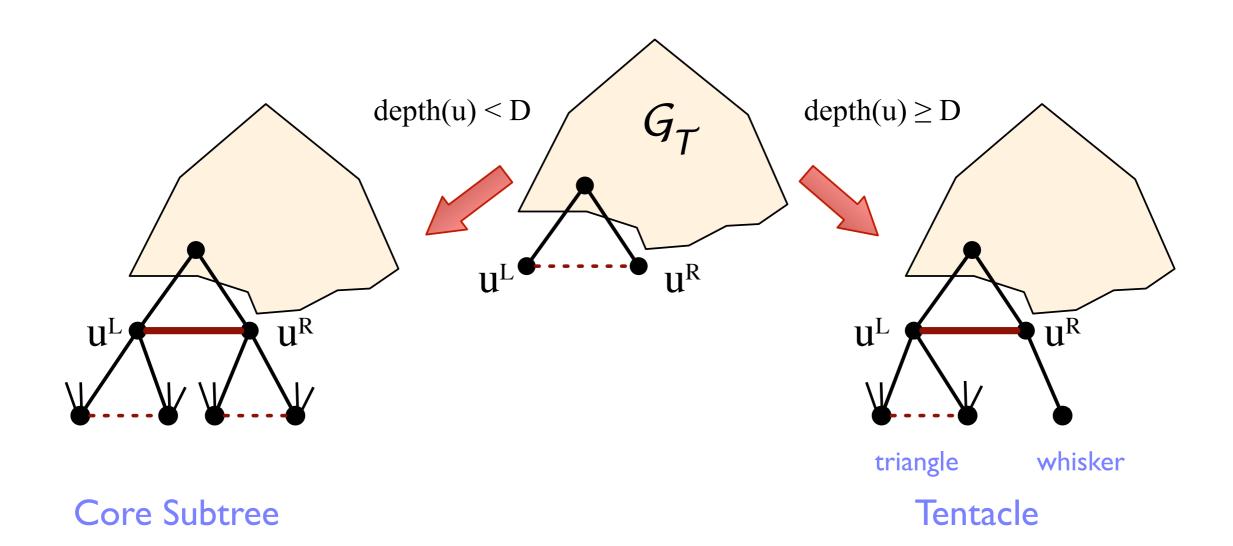
### Lower bound of 6 on any strategy

• graph generated by strategy is described by a "skeleton tree"



### How the adversary extends the tree

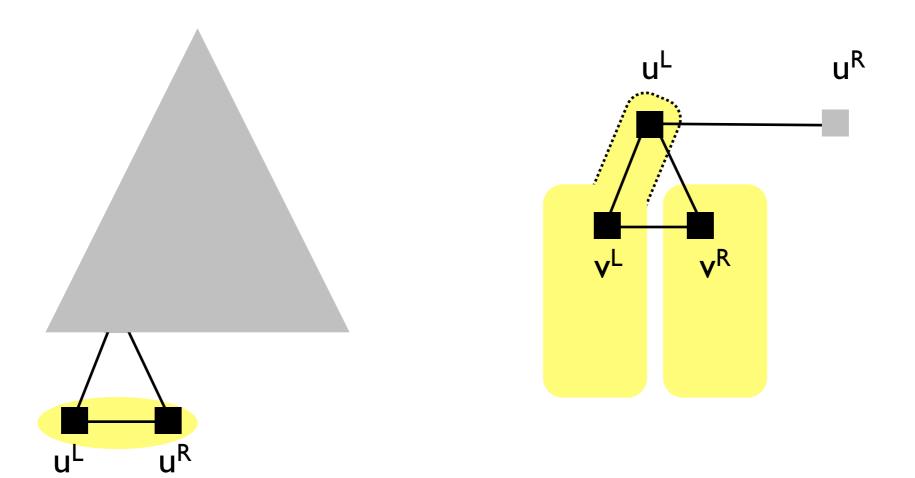
• if the strategy collects the edge (u<sup>L</sup>,u<sup>R</sup>)



### An adversarial clique partition

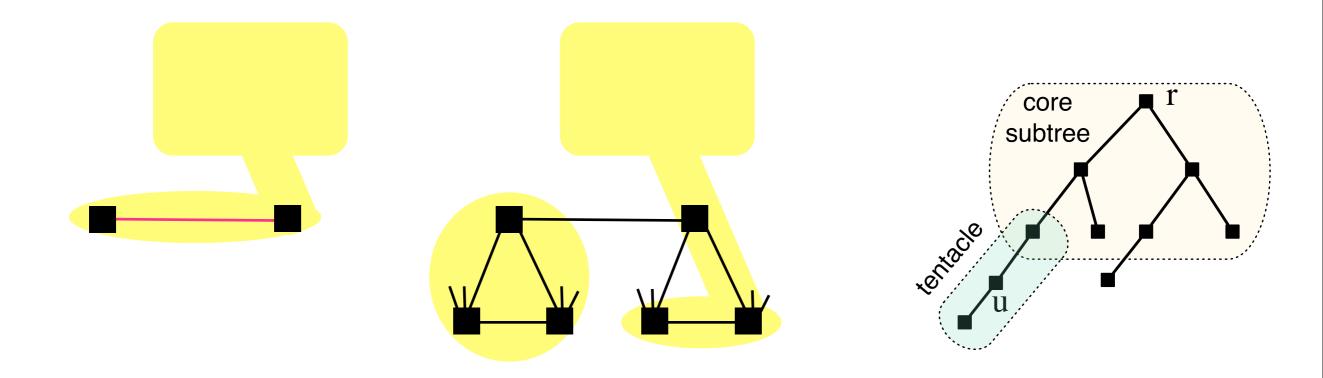
#### Bottom up description:

- If u is a leaf, (u<sup>L</sup>,u<sup>R</sup>) are in a clique
- If u has a left son v,  $u^L$  is added to one of the cliques containing  $v^L$  or  $V^R$
- If u has a right son v, (idem)



#### The argument

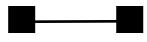
- We show that for every traversal edge collected by the strategy, the adversary releases more vertices and can increase his gain by at least 6
- If the strategy decices to stop at some point, the ratio is  $\geq 6$
- If the game lasts long enough, the adversary could stop, as his gain is quadratic in tentacle length, while strategy's gain is only linear



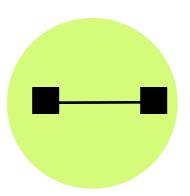
#### MinCC

Adversarial argument:

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- Algorithm has to merge this edge, otherwise ratio would be I/0

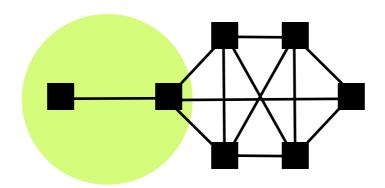


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Partition produced by the algorithm

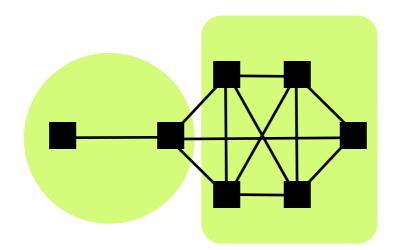
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Partition produced by the algorithm

 Algorithm can merge only part of the clique. Ratio is (n-2)/1

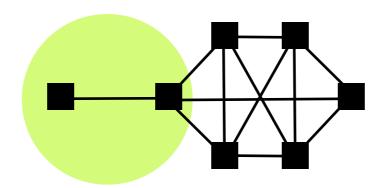
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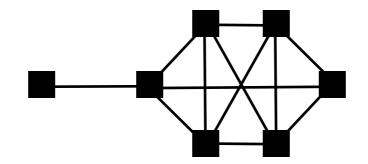
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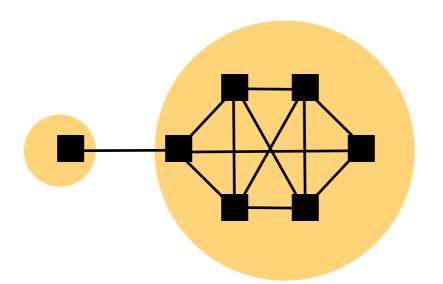
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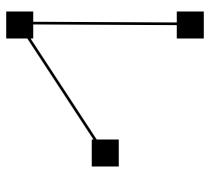
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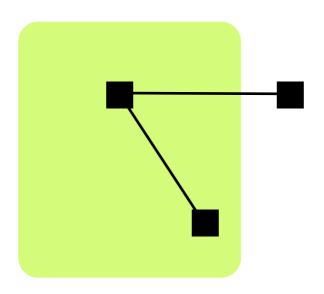


Optimal partition

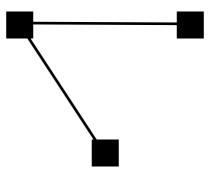
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- **key observation:** for 3 vertices connected by 2 edges, at least one of the edges is a non-clique edge



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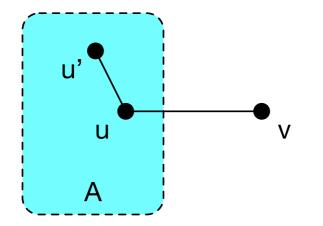
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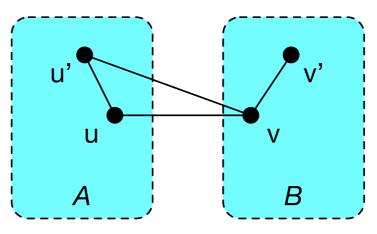


- compare a greedy solution ALG with optimal solution OPT
- charging scheme: charge every non-clique edge in ALG to non-clique edges by OPT
- show: that every non-clique edge obtains at most n-2 charges

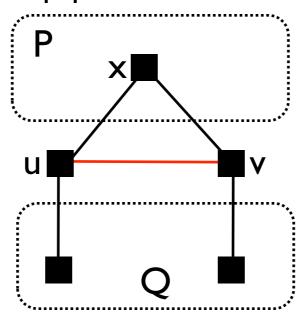
- Given non-clique edge uv in ALG:
  - if uv is also non-clique edge in OPT:
     self-charge uv to uv
  - else proximate charge uv
     in equal fractions to all non-clique edges in OPT adj to uv

- Claim every non-clique edge uv in OPT has an adjacent non-clique edge in OPT
  - Say v arrived after u. Let A be a clique in ALG when v arrived with  $u \in A$ .
  - Why did Greedy not add v to A?
  - Well the clique B containing v could not be merged with A.
  - There must be 3 vertices connected by only 2 edges: either uv and some vertex in A or v and some vertex in A and some in B





- Count how much charge can a non-clique edge uv in OPT obtain
  - P = set of vertices connected to both endpoints
     Q= set of vertices connected to a single endpoint
  - proximate charge from Q is at most |Q|
  - for every  $x \in P$ , one of uv or ux must be non-clique edge in OPT Hence if ux proximate charges to uv, then with fraction  $\leq \frac{1}{2}$
  - Charge from P is at most |P|/2.



- We have  $|P|+|Q| \le n-2$
- Claim  $|P|/2+|Q|+1 \le n-2$ 
  - ok if uv is cluster edge in ALG
  - ok if  $|P| \ge 2$
  - ok of Q contains cluster edges in ALG
  - case |P|≤ I and Q contains only non-cluster edges in ALG cannot happen.
     Greedy would have clustered uv together.

